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Regularity extraction across species:
associative learning mechanisms shared by human and non-human primates

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Running Head: REGULARITY LEARNING

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Abstract

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Extracting the regularities of our environment is a core cognitive ability in human and non-human primates. Comparative studies may provide information of strong heuristic value to constrain the elaboration of computational models of regularity learning. The current study illustrates this point by testing human and non-human primates (Guinea baboons, *Papio papio*) with the same experimental paradigm, using a novel online learning measure. For *local* co-occurrence regularities, we found similar patterns of regularity extraction in baboons and humans. However, only humans extracted the more *global* sequence structure. It is proposed that only the first result that is common to both species should be used to constrain models of regularity learning. The second result indicates that the extraction of global regularities cannot be accounted for by mere associative learning mechanisms and suggests that humans probably benefit from their language recoding abilities for extracting these regularities. We propose to use a comparative approach to address a series of remaining theoretical questions, which will contribute to the development of a general theory of regularity learning.

Keywords: regularity extraction; statistical learning; implicit learning; associative learning; verbal recoding

47 Statistical learning – the ability to extract and encode environmental regularities –
48 appears as a key feature of human cognitive systems and has been a domain of intensive
49 research over the last 20 years (see Frost, Armstrong, Siegelman, & Christiansen, 2015, and
50 Thiessen, Kronstein & Hufnagle, 2013, for reviews, but also e.g., Estes, 1950; Restle, 1970,
51 for earlier pioneer work). It is thought to play a key role in the segmentation of continuous
52 input, prediction, discrimination and categorization, shaping our basic representations of the
53 environment (Frost et al., 2015).

54 Historically, before the ‘statistical learning’ wave, similar issues were addressed in the
55 field of ‘implicit learning’. The latter term captures the observation that some forms of
56 learning occur after the mere repeated exposure to regularities (or rule systems, as in artificial
57 grammar learning experiments, e.g., Reber, 1967), with no intention of learning and no clear
58 awareness of what has been learned (Cleeremans, Destrebecqz, & Boyer, 1998; Shanks,
59 2005). Some authors, such as Conway and Christiansen (2006), have proposed to merge the
60 two terms (i.e., ‘implicit statistical learning’) to cover the general learning ability to extract
61 and encode different forms of environmental regularities.

62 Others, like Perruchet (2005; see also Perruchet & Poulin-Charronnat, 2012), have
63 argued that ‘statistical learning’ is nothing more than a new terminology corresponding, in
64 fact, to the old domain of associative learning (e.g., Hebb, 1961; Mitchell & Le Pelley, 2010;
65 Shanks, 1995). In this view, the extraction of regularities is understood as the formation of
66 new larger units also called ‘chunks’. This process is supported by associative learning
67 mechanisms, which itself is considered a by-product of the concurrent attentional processing
68 of multiple elements (or small units). Learning can also be qualified as ‘implicit’ as it doesn’t
69 require awareness of what is learnt nor the intention to learn (see also Perruchet & Pacton,
70 2006, Perruchet & Vinter, 2002). In that perspective, implicit statistical learning and
71 associative learning are considered as two sides of the same coin, the former having a broader

72 scope (including issues related to various aspects of language processing) compared to the
73 latter that was more concerned by the formation of simple associations or by operant
74 conditioning behaviors.

75 Basic associative (or implicit statistical) learning mechanisms are certainly shared by
76 human and non-human primates (e.g., Wilson, Marslen-Wilson, & Petkov, 2017), and
77 possibly by all species equipped with a nervous system (e.g., chicks: Santolin, Rosa-Salva,
78 Regolin, & Vallortigara, 2016; songbirds: Chen, van Rossum, & Ten Cate, 2015; rodents:
79 Toro, Nespors & Gervain, 2016). This raises the question which aspects of the human ability
80 for regularity extraction can be related to those in non-human primates. The present study
81 aims to address this question by a direct behavioral comparison between humans and
82 Guinea baboons (*Papio papio*) in the same experimental paradigm. This paradigm provides
83 an online measure of regularity extraction at different levels of integration. We argue that the
84 use of an online learning measure on the one hand and the study of non-human primates on
85 the other hand form a valuable approach to overcome two difficulties that characterize the
86 existing literature.

87 The first difficulty is that the temporal dynamics of regularity extraction is frequently
88 not considered. The seminal study of Saffran, Aslin, and Newport (1996) is often considered
89 as the critical starting point in the study of statistical learning, and several theoretical accounts
90 and computational models of this phenomenon have been proposed (e.g., Frank,
91 Goldwater, Griffiths, & Tenenbaum, 2010; French, Addyman, & Mareschal, 2011; Perruchet
92 & Vinter, 1998; Pothos, 2007). The empirical evidence used to elaborate these models is
93 mainly derived from studies using the same artificial language learning paradigm. In this task,
94 participants are exposed to an artificial language composed of few polysyllabic nonsense
95 words (e.g., 4) that are auditorily presented without any pause between words. After this
96 exposure phase, participants are asked to indicate which one of two test sequences looks more

97 familiar. The main dependent variable used to test models is therefore an offline measure that
98 informs us about which kind of regularities can be learned but that does not provide any
99 information regarding the temporal dynamics of learning (see e.g., Siegelman, Bogaerts, &
100 Frost, 2017, for a detailed discussion of the problems of offline learning measures). In
101 contrast to offline measures, online measures are obtained by recording the performance of
102 participants during the exposure to the regularities and can therefore provide information on
103 the temporal dynamics of regularity extraction. The serial response time task (Nissen &
104 Bullemer, 1987) is one good example of such online measure. In this task, participants
105 respond to sequences of stimuli that appear one-by-one at various locations on a computer
106 screen. If the sequences include regularities (allowing for the prediction of upcoming
107 locations), then participants speed their response times (RTs) if they manage to extract these
108 regularities (see also Batterink, 2017; Misyak, Christiansen, & Tomblin, 2010; Siegelman,
109 Bogaerts, Kronenfeld, & Frost, 2017, for other examples of online learning measures).

110 A second difficulty is paradoxically the strong focus on human (adult) participants.
111 Indeed, during the exposure phase, participants may develop strategies or explicit learning
112 procedures (like repeating internally some sequences of syllables) and their resulting
113 performance is certainly influenced and biased by various forms of explicit recoding
114 processes. Testing human infants without any advanced language and reasoning abilities (like
115 the original Saffran et al. study did, followed by many others, e.g., Bulf, Johnson, & Valenza,
116 2011; Singh, Reznick, & Xuehua, 2012) could be a solution to overcome that difficulty.
117 However, the study of infants also brings other procedural difficulties because the measures
118 that can be recorded for this population (for example, the head-turn procedure) are indirect
119 and much noisier (i.e., less reliable). Testing non-human primates allows us to study
120 regularity extraction in the absence of any bias due to language experience and the related
121 ability to verbally recode regularities.

122 Previous studies that adopted a comparative approach to study statistical learning were
123 mainly concerned with discovering differences between human and non-human primates
124 (e.g., Fitch & Hauser, 2004; Wang, Uhrig, Jarraya, & Dehaene, 2015). That logic is derived
125 from a research tradition that searched for a critical distinctive feature that could distinguish
126 animal communication systems from human language. For instance, Hauser, Chomsky, and
127 Fitch (2002) put forward the ability to process and produce recursive structures as a
128 fundamental distinctive feature that sets humans apart from other species. However, as argued
129 by Pinker and Jackendoff (2005), there are certainly many other critical differences between
130 human and non-human primates that can account for their distinct cognitive trajectories (see
131 also, Fagot, Malassis, Medam, & Montant, in press).

132 Here we propose an alternative perspective stating that we can increase our
133 understanding of the precise dynamics of regularity learning processes by looking at the
134 *common* patterns produced by human and non-human primates in online experimental
135 paradigms. As mentioned above, it is obvious that human adults can make use of both implicit
136 associative learning mechanisms and explicit recoding strategies based on their language
137 abilities to perform regularity extraction tasks. Non-human primates miss the language tools
138 that humans can use to explicitly recode regularities. One can therefore safely assume that
139 non-human primates mainly rely on associative learning mechanisms in these tasks, and that
140 these mechanisms are shared with humans. Therefore, any common pattern of performance
141 between human and non-human primates should reflect common fundamental properties of
142 these learning mechanisms. Alternatively, any difference could be related to the use of
143 language recoding abilities and should therefore be considered with caution for constraining
144 the development of computational models.

145 We now illustrate this proposition by comparing the performance of human and non-
146 human primates in a novel task that has been designed to combine the serial response time

147 task and the artificial language paradigm (Franco & Destrebecqz, 2012). Human adults and
148 baboons had to touch a red circle appearing successively at nine different locations of a
149 computer screen. The dot to follow moved on the screen along paths containing statistical
150 regularities. The use of this task allowed us (1) to test the two populations with the exact
151 same experimental procedure, (2) to provide detailed information on the temporal dynamics
152 of regularity extraction, and (3) to compare humans and baboons at different levels of
153 integration, at the local level within the sequence (i.e., co-occurrences between individual
154 elements), or at the level of the global sequence structure (see the Method section below for
155 an operational definition of the distinction between local and more global regularities). Note
156 that part of the primate data was reported in Minier, Fagot, and Rey (2015).

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Methods

159 Participants were ten Guinea baboons (*Papio papio*, age range 3–15.5 years) from the
160 CNRS primate facility in Rousset (France) and 5 human adults (age range 20–24 years) from
161 Aix-Marseille University.

162 Baboons live within a larger group of 26 individuals, within a 700 m² outdoor
163 enclosure and had a permanent access to ten Automated Learning Devices for Monkeys
164 (ALDM, for a detailed description, see Fagot & Bonté, 2010; Fagot & Paleressompouille,
165 2009) equipped with a 19-inch touch screen and a food dispenser. The main feature of ALDM
166 equipment is that a radio frequency identification reader (RFID) identifies each baboon via a
167 microchip implanted in each arm. The baboons can therefore participate to the research at
168 will, without being captured, as the test programs recognize them automatically. All baboons
169 had previously participated to numerous computerized experiments using the ALDM test
170 systems. The experiment was controlled by the E-Prime software (Version 2.0, Psychology
171 Software Tools, Pittsburgh).

172 A trial began with the presentation of a fixation cross at the bottom of a touch screen.
173 The cross stayed on the screen till it was pressed. After pressing on it, the fixation-cross
174 disappeared and immediately 9 crosses representing locations were displayed on the screen,
175 one of them being replaced by the target, a red circle. When the target was touched, it
176 disappeared and was replaced by the cross. The next cross/location in the sequence was then
177 replaced by the red circle until the end of the sequence. Reward (a small pellet) was provided
178 at the end of a sequence of nine touches.

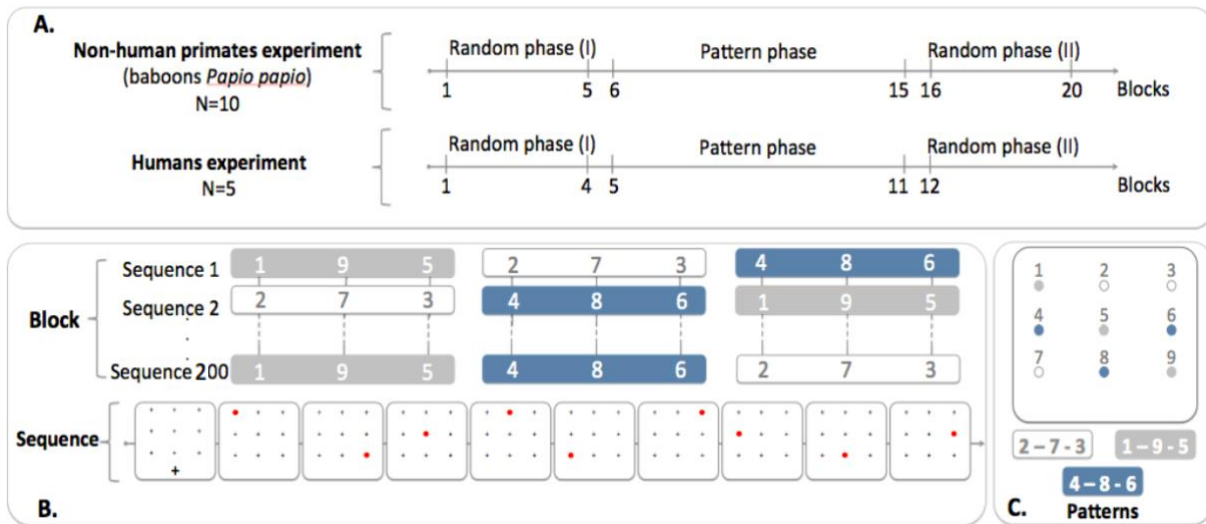
179 If participants touched an inappropriate location (incorrect trial), or failed to touch the
180 screen within 5,000ms after the red circle's appearance (aborted trial), a green screen was
181 displayed for 3000ms (baboons) / 1000ms (humans) as a marker of failure. Aborted trials
182 were not counted as trials and were therefore presented again, while incorrect trials were not.
183 The time elapsed between the appearance of the red circle and the participant's touch on this
184 circle was recorded as the response time (RT). To learn the task, baboons initially received
185 trials that were rewarded after one touch, after which the number of touches in a trial was
186 progressively increased up to nine. Humans were simply instructed to touch the red circle as
187 quickly as possible. They were also informed that each trial began by the presentation of the
188 yellow cross at the bottom of the screen followed by a sequence of nine touches on the
189 moving red circle.

190 To equate for the motor difficulty of the sequences to be produced, each participant
191 was first tested on 5 blocks (baboons) / 4 blocks (humans) of 200 random trials (called
192 "Random I phase"), each composed of a random ordering of nine locations, without
193 immediate repetition. A baseline measure for all possible transitions from one location to
194 another was computed by calculating mean RTs for each transition at the group level (i.e., the
195 entire group of baboons on the one hand and of human participants on the other hand).

196 After this Random I phase, participants were exposed to trials including statistical
197 regularities (hereafter, “Pattern phase”). Three independent regularities, each composed of
198 three fixed locations were constructed ($R_1 = 'A_1B_1C_1'$; $R_2 = 'A_2B_2C_2'$; $R_3 = 'A_3B_3C_3'$). To
199 study the extraction dynamic of these regularities, we carefully selected these three patterns so
200 that the mean RTs for the initial transition ($'A_iB_i'$) and final transition ($'B_iC_i'$) would not be
201 statistically different considering the baseline measurements obtained for these transitions
202 during the random phase. By matching these *local* adjacent dependencies at the onset of the
203 Pattern phase, it was possible to study the fine-grained evolution of these RTs that provide a
204 direct behavioral index of regularity extraction.

205 Moreover, to study the extraction dynamic at a more complex and *global* level, the
206 three regular patterns appeared in each sequence of nine touches, increasing the predictability
207 of each pattern in the sequence (1/3, 1/2, 1). For example, if participants are exposed to the
208 regular patterns R3 followed by R1, then the last regular pattern will be R2. If they manage to
209 extract such a complex regularity, we should then observe a decrease in RTs for the first
210 element of the last displayed regular pattern (in our example, for A_2).

211 During the Pattern phase, participants performed 10 (baboons) / 7 (humans) blocks of
212 200 trials each, one trial being composed of a random combination of the three regular
213 patterns. Finally, participants performed a last series of 5 (baboons) / 1 (humans) random
214 blocks (“Random II phase”) that had the same structure as the Random I phase (see Figure 1).



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217 Figure 1: Experimental procedure for baboons and humans across the whole experiment (A). Experimental
 218 procedure at the block- and trial level (B). Patterns of locations on the touch screen used with humans (C).
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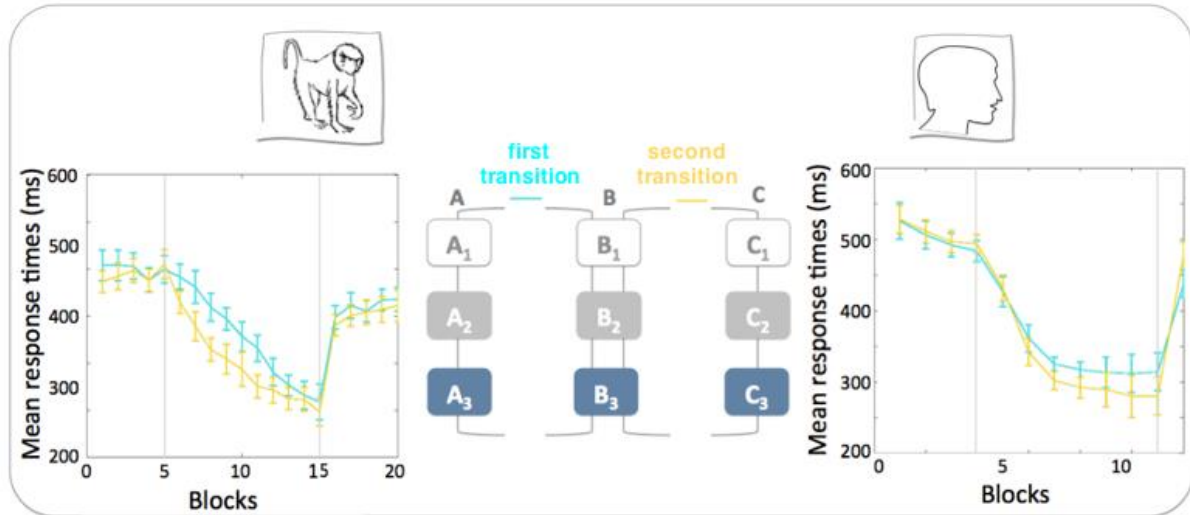
Results

221 Incorrect trials were removed from the dataset (7.6% for baboons and 5.9% for
 222 humans), as well as RTs greater than two standard deviations from the mean (computed for
 223 each subject and each block, 4.2% for baboons and 3.6% for humans).

224 The first analysis concerned regularity extraction at the local level. Minier et al. (2015)
 225 reported an advantage of the second transition (i.e., BC) over the first one (i.e., AB) in
 226 baboons, with RTs on C decreasing faster than RTs on B. We therefore ran the same 2
 227 (Transitions) * 7 (Block) repeated measures ANOVA on the mean RTs of humans. Mauchly's
 228 test indicated a violation of the sphericity assumption for the block factor ($\chi^2(44)=71.7$,
 229 $p<0.05$), so Greenhouse-Geisser estimates ($\epsilon=0.11$) were used to correct for degrees of
 230 freedom. We found a significant effect of Transition ($F(1,9)=14.9$, $p<0.01$, $\eta^2_p=0.62$), first
 231 transition RTs being slower than those of second transitions, and a significant effect of Block
 232 ($F(2.88, 25.9)= 36.5$, $p<0.001$, $\eta^2_p=0.80$) as the response latencies decreased through learning.
 233 Finally, the Transition * Block interaction was also significant ($F(9,81)=4.9$,
 234 $p<0.001, \eta^2_p=0.33$). Contrasts between first and second transitions for each block revealed a

235 significant difference in blocks 1 to 8, but not in blocks 9 and 10. As shown in Figure 2, the
 236 human results match those of baboons with a faster decrease of RTs on C than on B.

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239 Figure 2: Evolution of mean RTs for the first (AB) and second (BC) transitions over blocks for baboons (on the
 240 left) and humans (on the right).

241

242 The second analysis concerned regularity extraction at a more global level,
 243 specifically, the predictability of the third pattern in the sequence given the first and second.
 244 As shown in Figure 3 (upper panel), the predictability within regular patterns is always equal
 245 to 1. Indeed, in each regular sequence, A_i was always followed by B_i that was always
 246 followed by C_i . However, the predictability of A varied across patterns depending on their
 247 position in the sequence of 9 touches. The first A of the first ABC regular pattern could occur
 248 with a probability of $1/3$, the second A with a probability of $1/2$, and the last A with a
 249 probability of 1. Of course, these probabilities depend on the ability of participants to extract
 250 the global statistical structure of the experiment.

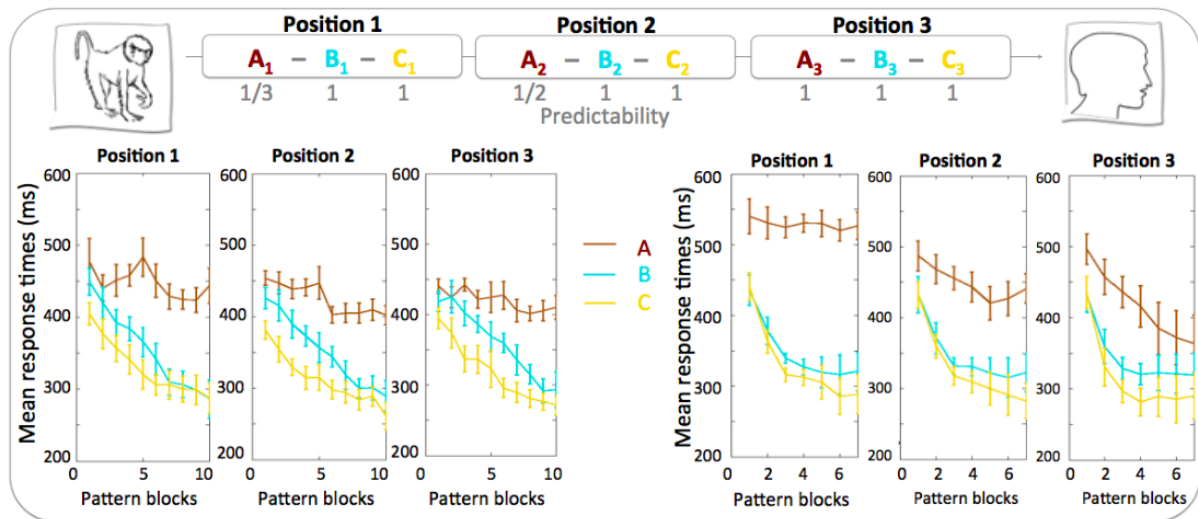
251 We thus considered RTs for the three patterns on the three different positions in the
 252 sequence. Because humans and baboons did not receive the same number of blocks, we ran
 253 two different ANOVAs, both including Place in the pattern (first = A, second = B or third =

254 C), Blocks (1 to 10 for baboons and 1 to 7 for humans) and Position of the patterns in the
 255 sequence (first, second or third) as within-subject factors.

256 For baboons, Mauchly's test indicated a violation of the assumption of sphericity for
 257 the Block factor ($\chi^2(44)=67.5, p<0.05$) as well as for the Position factor ($\chi^2(2)=6.3, p<0.05$),
 258 so Greenhouse-Geisser estimates ($\epsilon=0.31$ and $\epsilon=0.62$, respectively) were used to correct for
 259 degrees of freedom. We found a significant effect of Position ($F(1.23, 11.2)=8.0, p<0.013,$
 260 $\eta^2_p=0.47$), and a significant effect of Block ($F(2.8, 25.2)=3.7, p<0.001, \eta^2_p=0.29$). The
 261 interaction between Block and Position were found to be significant as well ($F(18,162)=1.8,$
 262 $p=0.026, \eta^2_p=0.17$). Helmert contrasts showed that the effect of Position was between the first
 263 position and the last two ($F(1,9)=8.9, p=0.02, \eta^2_p=0.5$) but not between the second position
 264 and the third ($F(1,9)=1.74, p=0.22, \eta^2_p=0.16$). Another ANOVA ran on the mean RTs of the
 265 first place of the patterns (i.e., A) with only the last learning block and Position as a within-
 266 participant factor with 3 levels (1st, 2nd and 3rd) showed a significant effect ($F(2,18)=4.9,$
 267 $p<0.05, \eta^2_p=0.35$). Helmert contrasts confirmed that this effect was significant between the
 268 first and two last positions ($F(1,9)=6.2, p=0.04, \eta^2_p=0.40$) but not between the second and the
 269 third positions ($F(1,9)=0.67, p=0.43, \eta^2_p=0.07$).

270 For humans, we found a significant effect of Position ($F(2,8)=36.83, p<0.001,$
 271 $\eta^2_p=0.90$), and a significant effect of Block ($F(6, 24)=7.0, p<0.001, \eta^2_p=0.64$). The
 272 interaction between Position and Block was also significant ($F(12,48)=13.57, p<0.001,$
 273 $\eta^2_p=0.77$). Helmert comparisons showed that the effect of Position was between the first
 274 position and the two last ($F(1,4)=51.5, p=0.02, \eta^2_p=0.98$), and between the second position
 275 and the third position ($F(1,4)=8.03, p=0.047, \eta^2_p=0.67$). A final ANOVA considered mean
 276 RTs of the first place in the patterns (i.e., A) in the last learning block only. Position was
 277 entered as within-participant factor with 3 levels (1st, 2nd and 3rd). This analysis showed a
 278 significant effect ($F(2,8)=36.7, p<0.0001, \eta^2_p=0.90$). Helmert contrasts indicated that this

279 effect was significant between the first and two last positions ($F(1,4)=68.0$, $p<0.001$,
 280 $\eta^2_p=0.94$) and between the second and the third position as well ($F(1,4)=14.3$, $p=0.02$,
 281 $\eta^2_p=0.78$). The evolution of mean RTs for baboons and humans over each block, each
 282 position within the sequence, and each place within the regular pattern is provided in Figure 3
 283 (lower panels). A clear difference between baboons and humans appears for the first element
 284 of the triplet when it occurred in Position 3 of the sequence (i.e., A_3): RTs decreased across
 285 learning blocks for humans while no decrease was observed for baboons.
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 288 **Figure 3:** Upper central panel: Predictability of each location in the sequence of nine touches. Lower panels:
 289 Evolution of mean RTs over blocks (1-10 for baboons and 1-7 for humans), positions (1, 2, or 3) and places
 290 within the regular patterns (A, B, or C) for baboons (on the left) and humans (on the right).
 291

292 Discussion

293 Two main findings were obtained in the present comparative study in which the
 294 performance of human adults and baboons were collected in the same regularity learning task.
 295 For regularities at the *local* level, human and non-human primates displayed a similar
 296 statistical learning dynamic: RTs decreased faster on the third location of a regular pattern
 297 (i.e., C) than on the second (i.e., B). At a more *global* level, we found different results for
 298 humans and baboons. In humans, RTs for the first element (i.e., A) of the third displayed

299 regular pattern (i.e., the 7th element in the sequence, which should become predictable over
300 the course of learning) decreased gradually across learning blocks while no such improvement
301 was observed for baboons.

302 The first result, already reported for baboons by Minier et al. (2015), indicates that the
303 two species had a similar dynamic of regularity extraction. In both species, RTs decreased
304 faster on C than on B in ABC regular patterns, suggesting that it is a general property that
305 should be captured by current computational models. As argued previously by Minier et al.
306 (2015), this pattern of results is inconsistent with theoretical propositions resting on the notion
307 of transitional probabilities between adjacent elements. Indeed, in our task, the transitional
308 probabilities from A to B and from B to C are all equal to one and are therefore insufficient to
309 account for the present data. Similarly, the TRACX model by French et al. (2011) predicts
310 that RTs should decrease faster on B compared to C given that the model is based on a left-to-
311 right acquisition of statistical regularities. Only the SRN model (Elman, 1990) predicts the
312 learning advantage of C over B. SRN assumes that learning is based on the development of
313 associations between the successive elements of the input that are frequently and consistently
314 encountered together. SRN encodes also the contextual information that precedes the
315 successive elements, and therefore C benefits from richer contextual information (i.e., the
316 preceding systematic sequence AB) while B benefits only from the systematic occurrence of
317 A.

318 Our second result indicates that only humans capture the more complex regularity
319 related to the predictability of the third regular pattern in the larger sequence. In that situation,
320 following the logic that we proposed, the absence of a common behavioral pattern of results
321 between human and non-human primates suggests that this kind of regularity cannot be
322 extracted by mere associative learning mechanisms. Computational models are therefore not
323 expected to account for this phenomenon that may require language recoding abilities.

324 Following a different line of reasoning, one may argue that the present results point to
325 a possible limitation of the learning capacities in non-human primates. The extraction of these
326 global regularities might indeed require a more complex learning mechanism or a larger
327 memory span for preceding elements. One would need however to specify what is the precise
328 nature of this learning mechanism and what would be the role of short-term memory span in
329 facilitating the extraction of such global regularities.

330

331 *Conclusions and avenues for future research*

332 The comparative approach taken in the current paper suggests that the mechanisms
333 underlying regularity extraction can be further understood by looking at patterns of
334 performance that are common to human and non-human primates. Based on the present
335 results we suggest that shared associative learning mechanisms can account for the extraction
336 of *local* regularities (i.e., co-occurrences) and that a general theory of regularity learning
337 could benefit from the large existing literature on associative learning (Mitchell & Le Pelley,
338 2010; Shanks, 1995). Moreover, the temporal dynamics of co-occurrence learning we
339 observed in both species suggests a learning advantage for the final stimulus of a repeated
340 (triplet) pattern, providing an important empirical constraint for models of regularity
341 extraction. Sensitivity to *global* regularities at the level of the entire sequence was observed
342 for humans only and might call for a theory that accounts for the interaction between basic
343 associative learning mechanisms and verbal recoding strategies.

344 Several important issues remain to be addressed to reach a general theory of
345 associative learning mechanisms and their role for regularity extraction in different situations.
346 We propose that the use a comparative approach can be a fruitful avenue for future research to
347 address a series of remaining theoretical questions, which we outline in more detail below.

348 A first series of questions concerns the role of the *timing* of co-occurrences in the
349 sensory input. Suppose that A and B are two sources of information that co-occur
350 systematically, A being always followed by B. Assuming no interfering information between
351 A and B, how does the dynamic of regularity extraction change as a function of the delay
352 between the presentation of A and the presentation of B? How many times A-B has to be
353 repeated in order to observe an extraction of the co-occurrence? What is the role of the delay
354 between two repetitions of A-B?

355 A second series of questions is related to the *sources of information surrounding* the
356 A-B co-occurrence to be extracted. A general theory of regularity learning should be able to
357 specify the role of factors such as the number and nature of interfering information between
358 two repetitions of A-B, the role of the similarity between the interfering information and each
359 element of the co-occurrence (A and B), the role of forward and backward inconsistencies
360 (i.e., the role of the statistical co-occurrence of A with another source of information, e.g., C,
361 and the interference of A-C on the extraction of A-B or, respectively, the co-occurrence of B
362 with a preceding source of information, e.g., D, and the interference of D-B on the extraction
363 of A-B), and finally, the effect of the presence of other co-occurrences (e.g., like E-F)
364 appearing between two repetitions of A-B.

365 A third series of questions concerns the *number of co-occurring elements*. What is the
366 regularity extraction dynamic when A-B is systematically followed by another information C
367 (an issue that has started to be addressed in the present study)? Similarly, what will happen if
368 we increase the chain of co-occurring elements? For ABCD sequences, for example, will we
369 observe an even faster decrease of RTs on D compare to C (because of the richer context) or
370 is the role of contextual information limited to a restricted time-window? And for longer
371 sequences, what is the effect of repeating a previously encountered element (e.g., like in the
372 sequence ABCAD)?

373 A fourth set of questions is related to the *learning of non-adjacent co-occurrences*
374 (Gómez, 2002 ; Pacton & Perruchet, 2008 ; Pacton, Sobaco, & Perruchet, 2015). Under which
375 conditions can we extract the co-occurrence of A and B when other sources of information are
376 placed between A and B? Clearly, if co-occurrence learning is supported by associative
377 learning mechanisms, the presence of interfering information between A and B will strongly
378 decrease the probability to extract this regularity. However, baboons have shown some ability
379 to process long-distance dependencies (Rey, Perruchet, & Fagot, 2012) indicating that the
380 learning of non-adjacent regularities should be accounted for by current computational
381 models of regularity learning.

382 To conclude, we have proposed an alternative way of using comparative studies to
383 better comprehend the fundamental mechanisms supporting regularity extraction. Rather than
384 focusing on the differences between species, we suggest focusing on common patterns of
385 performances to determine the empirical evidence that should constrain the elaboration of
386 computational models. By employing online measures, we can generate fine-grained
387 behavioral results that can inform models about the precise dynamics of regularity extraction
388 mechanisms. We have suggested that this approach can be quite powerful in testing the
389 predictions of computational models. Finally, we have outlined a list of questions that would
390 need to be addressed to reach a deeper understanding of associative learning mechanisms in
391 the context of regularity extraction.

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Acknowledgments

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