1	Towards rapid analysis with XRF sensor for assessing soil fertility attributes:
2	effects of dwell time reduction +
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4	Tiago Rodrigues Tavares ¹ , José Paulo Molin ² , Elton Eduardo Novais Alves ³ , Fábio Luiz
5	Melquiades ⁴ , Hudson Wallace Pereira de Carvalho ¹ , Abdul Mounem Mouazen ⁵
6	
7	¹ Laboratory of Nuclear Instrumentation (LIN), Center for Nuclear Energy in Agriculture (CENA),
8	University of São Paulo (USP), Piracicaba, São Paulo 13416000, Brazil
9	² Laboratory of Precision Agriculture (LAP), Department of Biosystems Engineering, "Luiz de
10	Queiroz" College of Agriculture (ESALQ), University of São Paulo (USP), Piracicaba, São Paulo
11	13418900, Brazil
12	³ CESFRA, AgroBioSciences, Mohammed VI Polytechnic University, BenGuerir, 43150, Morocco.
13	⁴ Laboratory of Applied Nuclear Physics (LFNA), Department of Physics, Londrina State University
14	(UEL), Londrina 86057970, Paraná, Brazil
15	⁵ Precision Soil and Crop Engineering Group (Precision SCoRing), Department of Environment,
16	Faculty of Bioscience Engineering, Ghent University, Coupure Links 653, Blok B, 1st Floor 9000
17	Gent, Belgium
18	* Corresponding author – <u>tiagosrt@usp.br</u> (T. R. Tavares)
19	⁺ The present study is part of the first author's Ph.D thesis presented to the University of São
20	Paulo.

22 Abstract

23 The analysis time used for the diagnosis of soil fertility attributes using portable X-ray 24 fluorescence spectroscopy (XRF) sensors (between 30 and 90 s) is too long for in situ 25 applications. The present study aimed at evaluating the trade-off between dwell time and XRF 26 performance for assessing soil fertility attributes. A total of 102 soil samples acquired in two 27 Brazilian agricultural fields were used, whose spectra were obtained using dwell times of 90, 60, 28 30, 15, 10, 7, 4, and 2 s to build and validate calibration models for clay, cation exchange 29 capacity, and extractable K and Ca. Results revealed that it is possible to make drastic reductions 30 in the XRF dwell time (from 90 to 2 s), while keeping excellent prediction performance [ratio of 31 performance to interquartile distance (RPIQ) between 3.52 and 8.32] for all the studied 32 attributes. A dwell time of only 2 s performed satisfactorily and is an analysis time suitable for 33 rapid in situ applications. In addition, it was shown that data from spectral databases previously 34 collected that used long dwell times (e.g., 30, 60, 90 s) can be extrapolated to fast applications 35 with shorter dwell times (e.g., 2 and 4s), once standardization by the detector's live time has 36 been performed. Anyhow, calibrations using a dwell time similar to the one of the validation set 37 tended to show superior results and are therefore recommended. This study addresses the need 38 and provides guidelines for optimizing XRF sensor analysis time for in situ applications in the 39 context of precision agriculture.

Keywords green chemistry; proximal soil sensing; soil mobile platforms; soil health; site-specific
soil management

42 **1. Introduction**

43 The application of X-ray fluorescence (XRF) sensors for the analysis of soil fertility related 44 attributes has evolved rapidly in recent years (Lima et al., 2019; Nawar et al., 2019; Tavares et 45 al., 2020a). The technique characterizes a wide range of soil elemental composition (*e.g.*, Si, K, Ca, Ti, Fe, Cu, among others), providing complementary information to other proximal soil 46 47 sensing (PSS) techniques, e.g., apparent electrical conductivity (EC_a) and diffuse reflectance 48 spectroscopy using visible and near-infrared regions (VNIR) (Javadi et al., 2021; Molin and 49 Tavares, 2019; Xu et al., 2019). Today, XRF sensors have become compact and are promising for 50 integration onto mobile platforms and/or robots (Bosco, 2013).

51 Portable XRF sensors have been applied manually for in situ analysis for heavy metals 52 determination in soils (Paulette et al., 2015; Weindorf et al., 2013) and geochemical evaluations 53 in soil trenches (Stockmann et al., 2016; Weindorf et al., 2012). Although these in situ analyses 54 have shown good analytical performances, the XRF analysis time (or dwell time) between 30 and 90 s, typically employed, is not compatible with automated in situ analysis for soil fertility 55 56 mapping (e.g., on-the-go applications), which require faster measurements. For example, both 57 EC_a and VNIR techniques have an almost instantaneous acquisition time (one second per point) 58 that allows on-the-go data acquisitions with high spatial density (e.g., > 250 data points ha⁻¹ at operating speeds of around 4 m s⁻¹) (Molin and Tavares, 2019). On the other hand, on-the-go 59 60 application using ion-selective electrodes (ISE) is of similar constrain to that of XRF, since the ISE 61 needs a relatively long dwell time to be in contact with the sample to stabilize its reading (*e.g.*, 62 approximately 10 to 15 s) (Adamchuk et al., 2007). Anyway, kinematic data acquisitions using ISE systems usually measure about 15 to 30 data points ha⁻¹ (Schirrmann et al., 2011), a similar 63 64 frequency of acquisition should be expected for the XRF if it would be used for on-the-go 65 measurement. Different studies have shown good predictive performances $(0.71 \le R^2 \le 0.91)$ for key soil fertility attributes (e.g., clay, cation exchange capacity (CEC), base saturation, and 66 67 exchangeable (ex-) nutrients) using XRF sensors (Andrade et al., 2020; Lima et al., 2019; Tavares 68 et al., 2020b). However, to the best of our knowledge no research has evaluated dwell times 69 smaller than 30 s and neither has searched for an optimal analysis time for rapid and accurate 70 soil attributes predictions.

Reducing the dwell time, increases the noise in XRF spectrum and thus reduces its analytical quality (Weindorf and Chakraborty, 2016). However, despite reducing their accuracy, the spectrum does not have its emission intensity, in counts of photons per second (cps), altered by reducing the dwell time, as can be seen in Figure 1. The intensity of an XRF spectrum is analyzed in cps when its total count is standardized by the detector's operating time (so-called 76 detector's live time). This standardization should be applied to XRF data because small variations 77 of the detector's live time (e.g., tenths of a second) are commonly observed when analyzing 78 multiple samples (Jenkins, 2012). Errors from this detector variation are avoided by 79 standardizing the XRF spectrum by the live time the detector presented when reading that 80 specific sample. Modeling XRF data (entire spectra or specific emission lines) in cps is a common 81 procedure within the XRF community (Rodrigues et al., 2018; Wolksa, 2005). However, such 82 procedure is not widespread among users from the soil science community, possibly due to the 83 popularization of using pre-programmed measurement packages for XRF soil analysis (Andrade 84 et al., 2021; Lima et al., 2019; Sharma et al., 2015; Silva et al., 2019, 2017), which do not require 85 the user to manipulate the spectral data. Even though, it also does not permit optimizing the 86 instrumental conditions, such as reducing scanning time (Tavares et al., 2020a).





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Fig. 1. X-ray fluorescence (XRF) spectra of a soil same sample collected with different scanning
times (90, 30 and 2 s), after being standardized by the detector's live time. Counts of photons
per second was abbreviated as cps.

92

93 XRF applications with reduced dwell time are common in analytical chemistry laboratories 94 that are specialized in this technique. The μ -XRF technique (a variant of the XRF technique) uses 95 a micrometric X-ray beam to map elements over the surface of a sample of interest. To cope 96 with the high spatial density of scans (e.g., > 300 spectrum per mm²), this approach uses a 97 reduced dwell time (*e.g.*, from <1 to 3 s) (Rodrigues et al., 2018). Both the absence of studies in 98 the literature that aim to optimize dwell time for *in situ* applications, as well as the possibility of 99 analysis with this technique employing dwell times shorter than 5 s, were the motivations to 100 evaluate the performance of the XRF sensor for predicting soil fertility attributes using reduced 101 dwell times. Thus, the following hypothesis (designated as hypothesis 1) was tested in this study: 102 "although reduced dwell times degrade the precision of the XRF prediction due to increasing 103 noise in spectra, it is still possible to drastically reduce the dwell time while maintaining 104 satisfactory performance for soil fertility prediction".

105 Even though in situ applications require reduced analysis time, the model calibration step 106 - that are commonly conducted under laboratory conditions - does not present a time 107 limitation for conducting its data acquisition, which could allow the use of longer dwell times to 108 reduce the problem of increased noise. In this case, models calibrated with longer dwell time 109 would be extrapolated in *in situ* spectra acquired with short dwell time (*e.g.*, 2s). Regarding this 110 issue, it is possible to raise the following question "what is the best dwell time for calibrating 111 predictive models that will be extrapolated in rapid XRF predictions during in situ applications 112 (e.g., 2 s)?" To answer this question, this study attempts to address the following hypothesis 113 (designated as hypothesis 2): "calibrations with higher dwell times (e.g., 90, 60, or 30 s) would 114 promote an optimal predictive performance when extrapolating models in spectra acquired 115 using reduced dwell times (e.q., 2s)".

116 This study aimed at evaluating the trade-off between the dwell time reduction and the 117 XRF performance for predicting chemical attributes related to soil fertility (i.e., clay content, CEC, 118 ex-K, and ex-Ca). In addition, this research assessed the performance of models calibrated with 119 data collected at different dwell time scenarios when extrapolated to fast analyzed data (i.e., 120 dwell time of 2). This latter analyses provides initial insights into the feasibility of using pre-121 existing databases and spectral libraries for the calibration of soil fertility models that will be 122 extrapolated to fast XRF applications. These evaluations will encourage further research on the 123 potential of XRF by users in the soil science and precision agriculture community whose research 124 is directed towards rapid analyses, e.g., in situ applications with sensors embedded in 125 agricultural machines and robots for soil mapping.

126 2. Material and Methods

127 The methodology applied in this study is schematically presented in Fig. 2. The study can 128 be divided into five steps: (i) soil sampling, (ii) soil fertility analyses, (iii) XRF analysis using 129 different dwell times, (iv) characterization of the dwell time effect on the XRF spectra and its 130 predictive performance, and finally (v) definition of an optimized dwell time for model 131 calibration seeking rapid soil fertility analysis.



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Fig. 2. Framework of the methodology applied for assessing the effect of dwell time reduction
in X-ray fluorescence sensor (XRF) for predicting clay, cation exchange capacity (CEC),
exchangeable potassium (ex-K), and exchangeable calcium (ex-Ca).

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137 2.1. Soil samples and fertility analysis

A total of 102 soil samples from Brazilian tropical fields were chosen for this study. These samples belong to the soil sample bank of the Laboratory of Precision Agriculture (LAP – ESALQ/USP), where they are stored after being air-dried and sieved at 2 mm. The chosen soil samples have wide ranges of variability in studied fertility attributes, necessary for the calibration of predictive models. Their texture classes vary among sandy loam, sandy clay loam, and clayey.

The contents of clay, CEC, ex-K, and ex-Ca were determined following the methods described by Van Raij et al. (2001), in which clay content was quantified by the Bouyoucos hydrometer method (Bouyoucos, 1951); extractable nutrients via ion exchange resin extraction (van Raij et al., 1986); CEC was calculated as the sum of soil potential acidity (H + Al) plus the sum of bases (ex-Ca + ex-Mg + ex-K); and H + Al was quantified via pH in the buffer solution method (SMP) (Quaggio et al., 1985). Contents of clay, CEC, ex-K, and ex-Ca were used as reference (Y-variables) for establishing the XRF-spectral modeling.

151 2.2. XRF measurements and scenarios of dwell time

An amount of about 10 g of each sample was analyzed with a portable XRF sensor. For
 this, soil samples were placed in a polyethylene cup of 31 mm diameter sealed with a 4-μm thick

154 polypropylene film (model 3520, SPEX, USA). A Tracer III-SD model XRF instrument (Bruker AXS, 155 Madison, EUA) was used for data acquisition. It is a portable device that is equipped with a 4 W 156 Rh X-ray tube and an X-Flash Peltier-cooled Silicon Drift Detector (Bruker AXS, Madison, USA) 157 with 2048 channels. This equipment scans an active area of 10 mm². During data acquisition, the 158 X-ray tube was configured at 35 kV and at 7 µA, while spectra were recorded under atmospheric 159 pressure and without filters, as suggested by Tavares, Mouazen, et al. (2020). These scanning 160 conditions were applied to eight different scenarios of dwell time (90, 60, 30, 15, 10, 7, 4, and 2 161 s). At each selected time, each sample was scanned in triplicate by slightly moving the position 162 of the sample cup after each replicate. The acquired spectra were normalized by the detector 163 live time, so that net peak area intensity was expressed in counts of photons per second. The 164 replicates of each sample were averaged for further analysis.

165 *2.3. Data analysis*

166 2.3.1. Effects of dwell time reduction on XRF's data

The characterization of XRF data as a function of dwell time reduction was performed by
observing the dispersion of signal-to-noise ratio (SNR) in Al, Si, K, Ca, Ti, and Fe Kα-lines. These
emission lines were chosen because they emit fluorescence at different energies (1.5, 1.7, 3.3,
3.7, 4.5, and 6.4 keV for Al, Si, K, Ca, Ti, and Fe, respectively), allowing to characterize the effect
of dwell time on emission lines that are likely to face different effects.

172 2.3.2. Effect of dwell time reduction on XRF's prediction performance

173 The 102 soil samples were split into two subsets, one for calibration (with 68 samples) 174 and the other for validation (with 34 samples) using the Kennard-Stone algorithm (Kennard and 175 Stone, 1969) applied on the measured soil fertility attributes (Y-variables). To evaluate the 176 performance of the prediction models as a function of dwell time reduction, a calibration model obtained with dwell time "X" using the calibration set was validated using its respective 177 validation set obtained with the same dwell time "X". In other words, models using XRF data 178 179 acquired at 15 s dwell time were validated on XRF data also acquired at 15 s. The intensity (using 180 the net peak area) of nine fluorescence lines (Kα emission lines of Al, Si, K, Ca, Ti, Mn, Fe, Ni, and 181 Cu) and two Thomson scattering peaks (Rh-K α and Rh-L α) were used as X-variables (Tavares et 182 al., 2020a). Multiple linear regression (MLR) analyses were applied for different dwell times 183 selected. All the calibration and validation steps were performed using the Unscrambler 184 software, version 10.5.1 (Camo AS, Oslo, Norway). Lastly, it is worth emphasizing that all 185 processed spectra (in the different calibration scenarios and also in the validation set) were 186 normalized by the effective dwell time (*i.e.*, detector live time), hence, in all cases the intensity 187 was modelled in counts of photons per second.

188 The prediction performance was evaluated by means of the root mean square error 189 (RMSE) and the ratio of performance to interquartile distance (RPIQ), the latter was calculated 190 as the ratio of the standard deviation (SD) of the laboratory measured soil property divided by 191 the RMSE in the prediction. Based on the RPIQ values, the prediction quality of developed 192 models were classified into four classes adapted from Nawar & Mouazen (2017): very poor 193 models (RPIQ \leq 1.40), fair models (1.70 \geq RPIQ > 1.40), good models (2.00 \geq RPIQ > 1.70), very 194 good models (2.5 \geq RPIQ > 2.0), and excellent models (RPIQ \geq 2.50). The Tukey test was also 195 applied to the residuals of the predictions performed with each dwell time (having a normal 196 distribution) to compare their performances.

197 2.3.3. Predictive performance of different dwell times for calibration of models to be
 198 extrapolated in applications with short dwell time

199 In order to find best dwell time for calibrating predictive models that will be extrapolated 200 in rapid XRF predictions during in situ applications (e.g., 2 s), the validation set with spectra 201 acquired with 2 s scanning time were used to extrapolate predictive models calibrated using 90, 202 60, 30, 15, 10, 7, 4, and 2 s dwell times. The prediction performance of clay, CEC, ex-K, and ex-203 Ca from the validation set was evaluated. This analysis was conducted because although in situ 204 applications demand a shorter analysis time, the model calibration step can be established 205 under a longer dwell time since it is usually performed under laboratory conditions having less 206 time constraint. The same strategies of data modelling and evaluation of model's performance 207 that were described in the 2.3.2. Section were also applied to the present analysis. Again, the 208 Tukey test was applied to the residuals of the predictions performed with each dwell time to 209 contrast their performances.

210 **3. Results**

211 *3.1. Soil fertility attributes*

The chosen samples presented high variability of all fertility attributes evaluated, with a coefficient of variation (CV) higher than 27% (Table 1). The Kennard-Stone algorithm allowed to select group of samples with comparable range and SD for both calibration and validation subsets (Table 1), which is essential to avoid undesirable influences on the prediction accuracy that are not related to the XRF sensor (Stenberg et al., 2010).

Table 1 Descriptiv	ve statistics of soil fertil	ity attributes for	the calibration and	validation dataset.					
	Clay	CEC ¹	ex-K ²	ex-Ca ²					
g dm ⁻³									
	Calibration set (n = 68)								
Min	175.00	37.50	0.90	8.00					

Mean	352.00	81.75	3.41	35.69					
Max	511.00	148.90	10.30	78.00					
SD ³	95.21	25.86	2.48	19.08					
CV ⁴ (%)	27.05	31.63	72.73	53.44					
	Validation set (n = 34)								
Min	175.00	42.50	0.90	8.00					
Mean	332.12	76.50	3.36	33.32					
Max	463.00	138.40	7.90	75.00					
SD	92.03	26.14	2.26	19.71					
CV (%)	27.71	34.17	67.39	59.16					

²¹⁹ 220

¹Cation exchange capacity, ²exchangeable (ex-) nutrients, ³standart deviation, ⁴coefficient of variation.

3.2. Effect of dwell time reduction on XRF data and its predictive performance

222 The noise was greater for this spectrum collected at a dwell time of 2 s than that of 90 s 223 (Fig. 3A), which reflects the reduction of measurement precision when reducing the dwell time. 224 The reduction of dwell time increased the SNR dispersion for all XRF emission lines but there is 225 no change in the average value (Fig. 2B-G). The standard deviation of fluorescence emission 226 decreases potentially as dwell time increases (Mondia et al., 2015), this relationship is 227 represented by a power function that was observed in the present data (Fig A1). This behaviour 228 is influenced by the element concentration in the sample, as well as by the energy of its 229 fluorescence emission (Ravansari et al., 2020), i.e., light elements suffer more interference than 230 heavy ones. Thus different elements show different response to dwell time reduction, as seen 231 in Fig A1. Among the emission lines evaluated, K presented the lowest SNR (< 4.5) with its CV 232 varying between 7 and 25%. K was the attribute that presented a greater variation of its signal 233 at shorter analysis times, with a CV of the SNR greater than 10% after 30s. Only the emission 234 lines of Al and Ca showed a CV greater than 10%, which happened only with a dwell time of 2s. 235 This instability in the sign of K should influence the prediction models that rely on this emission 236 line as the most important predictive variable.



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Fig. 3. Effect of dwell time reduction on XRF spectra (A). Signal-to-noise ratio (SNR) is shown for the K-lines of Al (B), Si (C), K (D), Ca (E), Ti (F), and Fe (G) obtained at different dwell times (2, 4, 7, 10, 15, 30, 60, and 90 s). The bars represent the standard deviation and the values in percentage represent the coefficient of variation of five XRF measurements (replicates) performed on the same soil sample after moving the sample cup position. Counts of photons per second was abbreviated as cps. Similar letters indicate no statistical difference at P<0.05 (Tukey test).

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Figure 4 shows the prediction performance of clay, CEC, ex-K, and ex-Ca models at different dwell times for the same dwell time adopted for the calibration and validation sets. Predictions of clay, CEC, and ex-Ca had a smaller performance variation when reducing the dwell time (with no statistical difference), showing an increase in RMSE ranging from 1.1 to 29.7 %. 250 On the other hand, ex-K was the attribute that showed a significant reduction in its prediction 251 performance compared to the best results obtained with 90 s dwell time model (with RMSE 252 increasing between 24.3 and 133.1 %). It can be seen that even with the observed RMSE 253 variations, the prediction performances of all fertility attributes remained excellent (RPIQ \ge 3.52) 254 over the entire dwell time reduction (from 90 to 2 s).

255 The different prediction behavior between clay, CEC, ex-K, and ex-Ca models must be 256 related to the SNR and the dispersion of the models' most important variables. It is important 257 to mention that the main variable for the clay model was the Fe-K α line, for the ex-K model the 258 K-K α , and for the Ca and CEC models the Ca-K α (Table A1). K-K α presented CV values greater than 10% from the 30s dwell time on, while the K-lines of Al and Ca only presented CV greater 259 260 values than 10% at the shortest dwell time (i.e., 2s). In turn, K-lines of Ti, Fe, and Si showed CV 261 < 4.7% in all dwell times (Fig. 2). Notwithstanding, ex-K prediction still showed an excellent 262 performance (RPIQ = 3.57) with points closely distributed around the 1:1 line (Fig. A2), even in 263 the most reduced dwell time scenario of 2 s.





Fig. 4. Effect of dwell time on X-ray fluorescence (XRF) sensor performance for clay (A), cation 266 267 exchange capacity (CEC) (B), exchangeable (ex-) K (C) and ex-Ca (D) prediction (using the 268 validation set, n = 34) for the same dwell time of both the calibration and validation set. The 269 performance was evaluated via the ratio of performance to interquartile distance (RPIQ) and 270 root-mean-square error (RMSE). The percentage values represent the variation of RMSE in 271 relation to the performance obtained with 90 s dwell time. The calibration and validation set 272 were obtained with the same dwell time as detailed in 2.3.2. Section. The most important 273 variables and the scatter plots of the models calibrated at 90 and 2 s are shown in Table A1 and 274 Figure A2 (Appendix Section), respectively. Different letters indicate a significant difference at 275 P<0.05 (Tukey test).

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277 3.3. Effect of model calibration using data with different dwell times

278 Figure 5 shows the performance of models calibrated using XRF data (of the calibration 279 set) acquired at different dwell times (90, 60, 30, 15, 10, 7, 4, and 2 s) when they were extrapolated to data (of the validation set) acquired at 2 s of dwell time, i.e., a dwell time 280 281 simulating what would be done in rapid applications. For all attributes, Tukey's test indicated no 282 statistical difference in predictive performance when using calibration sets with different dwell 283 times. Despite the absence of statistical difference, it was observed that the ex-K models tends 284 to perform better as the dwell time of the calibration set comes closer to the dwell time of the 285 validation set. For example, the prediction of ex-K using the calibration set at 7, 4, and 2 s has 286 22, 31, and 34% lower errors than when using the models with 90 s dwell time. This behavior 287 was not observed for clay, whose prediction showed stable trend across the different dwell times adopted in the calibration set (with RMSE ranging from 26.70 g dm⁻³ at 90 s to 29.4 g dm⁻ 288 289 ³ at 2 s, representing a variation of 10%). Although the predictions of CEC and ex-Ca showed the 290 best performance when calibrated and validated with the same dwell time of 2 s (with RPIQ 291 values of 3.52 and 5.50, respectively), this tendency, i.e., improve the predictive performance 292 as the dwell time of the calibration set approaches that of the validation set, cannot be clearly 293 observed for these attributes, as can be done for the ex-K.







Fig. 5. X-ray fluorescence (XRF) performance for clay (A), cation exchange capacity (CEC) (B),
 exchangeable (ex-) K (C) and ex-Ca (D) prediction, using different dwell times (90, 60, 30, 15, 10,
 7, 4, and 2s) in model calibration. The results represent the extrapolation of these different

calibration scenarios in the validation set (n = 34) that was analyzed with 2 s of dwell time. The performance was evaluated via the ratio of performance to interquartile distance (RPIQ) and root-mean-square error (RMSE). The percentage values represent the variation of RMSE in relation to the performance obtained with 90 s dwell time. Similar letters indicate no statistical difference at P<0.05 (Tukey test).

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305 The different prediction behavior among the models of clay, CEC, ex-K, and ex-Ca must be 306 related to the SNR and the dispersion of the models' most important variables (Table A1). As 307 discussed in the topic below, the greater variation in XRF measurements (i.e., lower analytical 308 precision) is related to a low SNR of the emission line in question. The Fe-K α emission line, that 309 is the main variable contributing in clay model (Table A1), had SNR larger than 1500 and CV 310 always smaller than 4% (Fig. 3). In turn, CEC and ex-Ca models rely mainly on Ca-K α emission line, whose SNR ranged between 13 and 21 and CV from 2.0 to 19.6% (with CV > 10% only for 2s 311 312 dwell time) (Fig. 3). Finally, the K-Ka emission line, main variable of ex-K models, had the lowest SNR (< 5) and CV variation greater than 10% from 30 to 2s of dwell time, which represents a 313 314 larger variation than that observed for the other emission lines (Fig. 3).

In summary, the results showed that there was no significant difference for clay, CEC, ex-Ca, and ex-K models, calibrated with 90, 60, 30, 15, 10, 7, 4 and 2 s data to predict these attributes on data acquired at 2 s of dwell time. Nevertheless, the CEC, ex-Ca, and ex-K models, especially the latter, showed a tendency to perform better as the dwell time of the calibration set comes closer to the dwell time of the validation set. Finally, the same trend of prediction described above was also verified when the models were applied to an independent validation set collected with 4 s dwell time (Figure A3, Appendix Section).

322 4. Discussion

323 The results evidenced that XRF readings lose precision as its dwell time is reduced, which 324 is explained by the increased noise at low dwell times. This behaviour occurs mainly for light 325 elements that are close to the detection limit (Ravansari et al., 2020), as observed for K, which 326 showed a greater variation in its fluorescence emission and a lower SNR (< 5). Obtaining stable 327 measurements with reduced analysis time is also related to the level of technology of the 328 equipment's detector. New generations of detectors have delivered lower noise at shorter 329 analysis times, and these advances expand the applications with XRF sensors (Bosco, 2013), such 330 as the one discussed in this paper.

Even though readings taken with a short analysis time reduce the precision compared to longer times, the XRF accuracy for predicting fertility attributes does not degrade expressively. This trend was observed even for the prediction of ex-K, whose models were based on the K 334 emission line, but achieved excellent prediction performances for all evaluated dwell times, 335 even for the most reduced dwell time scenario of 2 s (RPIQ = 3.57). Therefore, it is possible to 336 drastically reduce the sensor's dwell time (*e.g.*, from 90 to 2 s), while maintaining satisfactory 337 predictive performances (RPIQ \geq 3.52). Thus, the authors accept the first hypothesis of this study 338 that although low dwell times degrade the XRF prediction accuracy, it is still possible to 339 drastically reduce the dwell time while maintaining satisfactory performance for soil fertility 340 prediction (namely, clay, CEC, ex-K, and ex-Ca). No study in the literature has evaluated the 341 prediction performance of soil fertility attributes using scanning time as short as that presented 342 in the current research. Evaluating dwell time of 60, 120 and 180 s for P prediction in leaf 343 samples, Sapkota et al. (2019) observed that the time of analysis had no significant influence on 344 the performance of the models, having R² ranging from 0.84 to 0.88. In tropical soils, some 345 authors have reported no significant differences in attribute predictions made with dwell times 346 of 30 and 60 s (Silva et al., 2019, 2018). Although the aforementioned studies did not evaluate 347 drastic reductions in analysis time, the absence of performance loss in XRF prediction when 348 using contrasting dwell times corroborates the results observed in the present study.

349 The accuracy to measure a given element with XRF set at short dwell times is linked to 350 intrinsic aspects related to its fluorescence emission line (i.e., lighter elements that have lower 351 fluorescence emission and lower energies are more affected), as well as to the concentration of 352 this element in the sample (Ravansari et al., 2020; Silva et al., 2021). That is, light elements with 353 low content in the analyzed soil sample (i.e., close to their limit of detection and with a lower 354 SNR) are more affected by the loss of accuracy when reducing the scanning time. This behavior 355 occurs because the fluorescence emission of these elements have a lower SNR and, therefore, 356 any external interference (i.e., physical and chemical matrix effects) will have a greater effect on 357 is intensity (An et al., 2021; Ernst et al., 2014). In this study, the lower SNR of the K emission line 358 (< 10) caused a higher interference in the ex-K prediction model when changing the dwell time. 359 Similarly, the clay, CEC, and ex-Ca models that were related to emission lines with higher SNR 360 (i.e., Fe-Ka for clay models and Ca-Ka for CEC and ex-Ca models), had a higher stability when 361 changing the dwell time. In addition, it is worth commenting that SNR values lower than 10 are 362 considered critical and lead to poor modelling results (Danzer and Currie, 1998), indicating that 363 the element present concentrations are closer to the limit of detection for the instrumental 364 conditions adopted. Optimizing the instrumental conditions to increase the K-K α SNR may be a 365 strategy to be considered in the future to improve the performance of ex-K prediction under 366 low dwell time conditions.

367 Regarding the effect of dwell time for model calibration, the results showed that, once 368 the data are standardized by the detector's live time, the model can be calibrated with dwell 369 times ranging from 90 to 2s and successfully extrapolated on data collected with dwell times of 370 4 and 2s (Fig. 5 and Fig. A3). So, spectral library data previously obtained with longer dwell times 371 (e.g., 30, 60, 90s) can be used for XRF applications with rapid measurements such that the 372 predictive performance will not significantly deteriorate due to different dwell times. Despite 373 the absence of a significant difference, models based on emission lines with lower SNR 374 (especially ex-K models in this study) showed a tendency to perform better as the dwell time of 375 the calibration set comes closer to the dwell time of the validation set. In light of these results, 376 it is suggested that the calibration step should be performed with spectral data acquired with 377 the same dwell time as the one intended to be implemented in the field. This can be suggested, 378 because the prediction accuracy using longer dwell times did not lead to a better performance 379 of predictions (Fig. 5 and Fig. A3), as raised by the second hypothesis of this study; hence, it was 380 rejected.

381 The findings show that XRF may be suitable for accurate *in situ* rapid analysis of key soil 382 fertility attributes. This knowledge is not widespread among XRF users as it is quite common to 383 use pre-programmed measurement packages (Andrade et al., 2020; Horta et al., 2015; Lima et al., 2019; Nawar et al., 2019; O'Rourke et al., 2016), which are factory calibrations (for 384 385 determining total elemental concentration), associated with a pre-established dwell time, 386 generally between 30 to 90 s (Weindorf and Chakraborty, 2016). Based on the results presented 387 in this study, XRF users within the precision agriculture and soil science communities should be 388 encouraged to use open systems that allow the optimization of dwell time, since this will enable 389 the expansion of XRF applications in such context.

390 Unlike laboratory measurements that are mainly conducted on dried and sieved samples, 391 in field applications fresh unprocessed soils are measured, which means that external factors, 392 such as soil moisture and roughness, will influence sensors' output (Horta et al., 2015; Mouazen 393 and Al-Asadi, 2018; Nawar et al., 2020). To support future *in situ* applications of XRF sensors for soil mapping, further studies should evaluate the combination of rapid XRF analysis on fresh 394 395 (wet) samples, representing the soil conditions at the time of data acquisition directly in the 396 field. Evaluation of similar solutions to those adopted to mitigate performance loss on the near 397 infrared and mid infrared spectroscopy sensors (Minasny et al., 2011; Nawar et al., 2020; Roger 398 et al., 2003) due to external factors, such as the moisture content, may be a next step to consider 399 for XRF analysis.

400 Conclusions

The results showed that reducing the dwell time of X-ray fluorescence (XRF) analysis decreases the precision of its data. In spite of that, it was possible to achieve excellent prediction performance [ratio of performance to interquartile distance (RPIQ) \ge 3.52] of soil fertility attributes (clay, cation exchange capacity, and exchangeable K and Ca) even after applying drastic reductions of XRF's dwell time (from 90 to 2 s).

In addition, this study also evaluated and suggested an optimized dwell time for model 406 407 calibration (which is generally conducted in the laboratory without time restriction) seeking 408 rapid soil fertility analysis. The results suggested that the best calibration models are those 409 conducted with the same dwell time as the validation set (e.g., calibrated and validated using 410 spectra acquired at 2 s of dwell time), refuting the idea that a longer dwell time should guarantee 411 a more accurate data for model calibration. In any case, using longer dwell times for model 412 calibration did not lead to statistically significant differences in the validation results. Therefore, 413 this research also indicates that previously existing spectral libraries can be used to calibrate 414 models that will be extrapolated on XRF data obtained from rapid measurements without 415 significant losses in performance.

These results allow bringing XRF closer to *in site* soil fertility mapping in the precision agriculture context. Researches are encouraged to combine reduced dwell times with the removal of other external factors affecting in *in situ* applications (*e.g.*, soil moisture, soil roughness, etc) to optimize the future use of XRF for *in situ* field applications.

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429 Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal relationships which have or could be perceived to have influenced the work reported in this article.

433 Appendix

Fig. A1 shows the exponential behavior of the standard deviation as a function of dwell time for the K-lines of Al, Si, K, and Ca. Table A1 shows the importance of the spectral variables used for the model calibration for predicting clay, CEC, ex-K, and ex-Ca, using the dwell times of 90 and 2 s.



438
439 Fig. A1 Scatter plots of dwell time versus standard deviation of Al-, Si-, K-, and Ca-K lines
440 obtained from five XRF measurements performed on the same soil sample after moving the
441 sample cup position.

442

443 **Table A1** Importance of X-ray fluorescence (XRF) variables for the prediction of clay, cation 444 exchange capacity (CEC), (ex-) K and Ca, using the dwell times of 90 and 2 s. The values presented 445 correspond to the t-value for each standardized coefficient obtained in the fitted regressions.

	Dwell time (s)	Al-Kα	Si-Ka	Κ-Κα	Са-Ка	Τί-Κα	Mn-Kα	Fe-Kα	Νί-Κα	Cu-Kα	Rh-Kα	Rh-Lα
clay	90	-0.61	-1.35	0.05	-0.79	-3.48	-0.31	6.56	0.11	-1.69	-1.66	0.92
Clay	2	-0.92	-2.16	-0.40	-0.80	-2.29	-0.35	7.13	-1.24	-1.73	0.25	-1.38
CEC	90	-1.67	0.17	1.72	4.67	3.20	-2.84	-1.27	-0.61	1.38	-0.67	0.86
CEC	2	-1.16	-0.41	1.08	4.00	3.45	-2.42	-1.06	-1.12	0.46	0.21	1.63
ov K	90	-1.92	0.35	16.18	-4.41	-0.16	-2.00	0.33	-1.36	-0.90	-1.23	-1.39
ex-K	2	-2.34	-1.34	7.14	-2.21	0.23	1.29	-0.58	0.59	-1.30	-1.37	-1.89
av Ca	90	-3.33	2.29	1.78	8.53	1.46	-3.65	1.92	-0.39	0.37	0.08	1.26
ex-Cd	2	-3.26	2.15	0.87	8.93	2.43	-3.34	2.97	0.12	-0.93	-0.57	-0.02

The emboldened values indicate a significant t-values at the probability level of 0.05; significant values were presented on grayscale, with the most important variables having the darkest color and vice versa.

Fig. A2 shows the scatter plots of predicted versus measured clay, CEC, ex-K, and ex-Ca, for the validations set (n = 34) of models that were calibrated and validated using dwell times of 90 and 2 s. Finally, the Fig. A3 shows the results for the dwell time optimization for calibrating models seeking *in situ* applications, a similar analysis to the one detailed in Section 2.3.3., but now replicating all the evaluated dwell times (90, 60, 30, 15, 10, 7, 4, and 2 s) in spectra acquired with 4 s of dwell time. The results (Fig. A3) show that the behavior was the same as that observed for 2 s (described in Section 3.3.).



456

457 Fig. A2 Scatter plots of predicted versus measured clay (A), cation exchange capacity (CEC) (B),
458 exchangeable (ex-) K (C) and Ca (D) using dwell times of 90 and 2s.



460

461 Fig. A3 Calibration performance using different dwell times (90, 60, 30, 15, 10, 7, and 4s) for the calibration of models for the prediction of clay (A), cation exchange capacity (CEC) (B), 462 463 exchangeable (ex-) K (C) and Ca (D). The results represent the validation of these different 464 calibration scenarios when replicated on the validation set (n = 34) scanned with 4 s of dwell 465 time. The performance was evaluated via the ratio of performance to interquartile distance (RPIQ) and root-mean-square error (RMSE). The percentage values represent the variation of 466 467 RMSE in relation to the performance obtained with 90 s dwell time. Similar letters indicate no 468 statistical difference at P<0.05 (Tukey test). 469

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